



Class of Structure of Dynamics

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Homework #5 (Total Points 100/100)

α_1 : 11th digit of your student ID

For Example if your student ID:

40044404135

$\alpha_1: 5$ if $\alpha_1 = 0 \Rightarrow \alpha_1 = 1$

Note: If the 11th digit of the student number is zero, the number 1 should be used for α_1 .

PROBLEM1:

Two identical pendulums, each with mass m and length l , are connected by a spring of stiffness k at a distance d from the fixed end, as shown in Figure 1.

- Derive the equations of motion of the two masses.
- Find the natural frequencies and mode shapes of the system.
- Find the free-vibration response of the system for the initial conditions $\theta_1(0) = a$, $\theta_2(0) = 0$, $\dot{\theta}_1(0) = a$, and $\dot{\theta}_2(0) = 0$

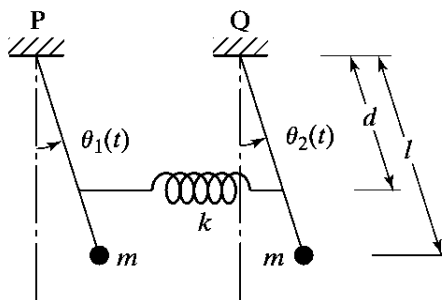


Figure 1-Two pendulums connected by a spring

PROBLEM2:

The floor masses and story stiffnesses of the three-story shear frame are shown in Figure 2.

- Derive the equations of motion of the three masses.
- Find the natural frequencies and mode shapes of the system.
- Find the free-vibration response of the system for the initial conditions:

$$v(0) = \begin{Bmatrix} 0.1 \times \alpha_1 \\ 0 \\ 0 \end{Bmatrix} \text{in}, \quad \dot{v}(0) = \begin{Bmatrix} 1 \times \alpha_1 \\ 0 \\ 0 \end{Bmatrix} \frac{\text{in}}{\text{Sec}}$$

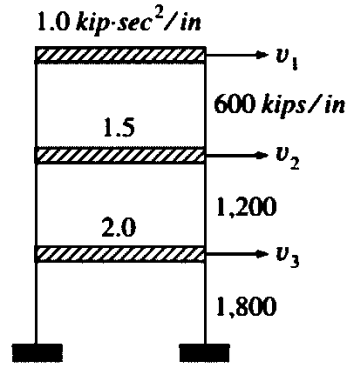


Figure 2- Three-story shear frame

PROBLEM3:

Consider the system shown in Figure 3, where $m = 70 \text{ ton}$ and $k = 6000 \text{ kN/m}$.

- d) Derive the equations of motion of the four masses.
- e) Find the natural frequencies and mode shapes of the system.
- f) Find the free-vibration response of the system for the initial conditions:

$$v(0) = \begin{Bmatrix} 0 \\ 0 \\ 0 \\ 2 \times \alpha_1 \end{Bmatrix} cm, \quad \dot{v}(0) = \begin{Bmatrix} 1 \times \alpha_1 \\ 0 \\ 2 \times \alpha_1 \\ 0 \end{Bmatrix} \frac{m}{\text{Sec}}$$

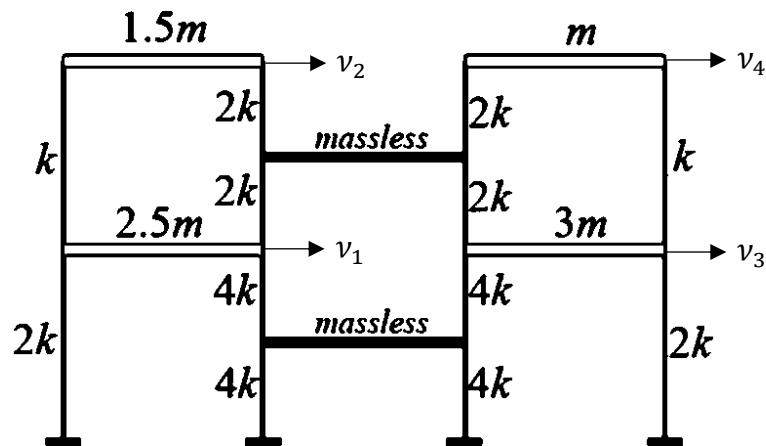


Figure 3

Hint: Static condensations : $k = k_{tt} - k_{to} k_{oo}^{-1} k_{ot}$, $k' = \begin{bmatrix} k_{tt} & \vdots & k_{to} \\ \cdots & \vdots & \cdots \\ k_{ot} & \vdots & k_{oo} \end{bmatrix}$

Good luck